



S01

Industrial Manipulators



Equipment designed for the "weightless" picking and moving of sacks - in polythene, cardboard, hessian, plastic fibre etc... Simple to use, this range of Dalmeccan machines allows the operator to move bags quickly, accurately and safely within the operating area.

The bags are picked with either a suction head or with a pneumatically clamp. Vacuum is created by an electric motor or by a Venturi ejector.

This range of manipulators offer maximum flexibility in type, design, dimensions and picking systems order to suit the specific requirements of the user and environmental conditions of the working area.

此设备是为了轻松搬运各种包状物体 - 聚乙烯, 纸板箱, 麻袋, 塑料光纤等。
使用简单, 机械手使操作人员在整个工作区域内快速, 精确安全的搬运包状物体。
戴尔麦克机械手可用吸盘或气动卡爪抓取包状物体。真空由电动马达或文丘里真空发生器产生。
机械手由客户定制, 运用合理的设计, 尺寸和抓取系统, 以符合用户的特殊要求, 适应各种环境。

包状物体 BAGS



S02

PSC type Partner manipulator, column mounted for palletization/depalletization of bags which are stacked up to about metres from floor level, fitted with lowered controls. Manipulator Partner PSC, 支柱式, 装备降低控制装置, 用于将包状物体装卸到栈板上, 并可将其堆积数米高。



S03

PSC type Partner manipulator, column mounted, equipped with suction head to pick bags from a pallet and to load them to a mixer. Manipulator Partner PSC, 支柱式, 装备吸盘, 从栈板上吸附包状物体, 并将其放进混合器里。



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S04

PSS type Partner manipulator, overhead trolley mounted version in Dalmec track. The operator picks bags from various pallets in the "picking" area and deposits them to a common pallet. Manipulator Partner PSS, 高架行车式, 配备戴尔麦克制造的轨道, 操作人员从抓取区各种栈板上抓取包状物体, 并将它们放在



f318

PSC type Partner manipulator, column mounted, equipped with suction head to pick bags from a pallet and loading them to a mixer. Manipulator Partner PSC, 支柱式, 装备吸盘, 可从栈板上吸附包状物体, 并将其放进混合器里。



PMC type Partner manipulator, column design, special low profile unit, to enable to operate in a room with low ceiling. The equipment allows the bags to be picked from a pallet and to be loaded onto a hopper.
 Manipulator Partner PMC, 支柱式, 特殊紧凑型, 在低房顶的空间中使用。此设备从栈板上抓取包状物体并将其放在送料斗中。



Suction device made from stainless steel. 由不锈钢制成的吸附装置



Highered and lowered dual commands. 高低双用



PSC type Partner manipulator, column design, overhead used to move bags from a sack filler to a pallet.
 Manipulator Partner PSC, 支柱式, 用作将袋灌装机的产品搬运到货架上。



PSC type Partner manipulator, fixed version, used to move bags from a sack filler to a pallet.
 Manipulator Partner PSC, 墙式, 用作将包装机的产品搬运到栈板上。

BAGS 包状物体

橡胶包 RUBBER BALES



PSC type Partner manipulator, column mounted, with suction head for handling rubber bales used for a trituration plant, equipped with an "extra pull" feature to facilitate detachment of the bale from the one underneath it. Manipulator Partner PSC, 支柱式, 装备吸盘, 搬运用于研磨设备所需要的橡胶包, 装备另一个“拉手”, 以便橡胶捆可以轻松分离。



Tooling head for handling rubber bales with independently swivelling suction cups. 使用独立的转动吸盘搬运多个橡胶包的工具头。



Manipulator with pneumatic jaws for handling rubber bales. The "slimline" design of the jaws allows for easy release into the bale's packaging. 装备气动卡爪的机械手, 用于搬运橡胶包。 “苗条”的卡爪可以很轻易的抓紧橡胶包。



Manipulator with pneumatically actuated grippers, which hold the bale by gripping into the product itself. 装备气动卡爪抓取包状物体的机械手



Manipulator with pneumatically actuated grippers, for handling jessian sacks containing coffee, cocoa and similar products.
 装备气动卡爪的机械手，用于抓取包装咖啡，可可及类似产品的麻袋

Manipulator with pneumatically actuated gripper picking system.
 装备气动卡爪的机械手



Manipulator with pneumatically actuated gripper picking system.
 装备气动卡爪的机械手



Manipulator with pneumatic clamping grippers which allows the bags to be inclined from the horizontal to the vertical and vice versa.
 装备气动钳制卡爪的机械手，把包状物体从横向到纵向倾斜，反之亦然。



Manipulator with retractable hooks for handling hessian sacks.
 装备可收缩吊钩的机械手，用于搬运大包货物。

JUTE BAGS 麻袋